### Music Source Separation and its Applications to MIR

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Part I: General principles of music source separation

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- Source separation and music
- Computational auditory scene analysis
- Probabilistic linear modeling
- Probabilistic variance modeling
- Summary and future challenges

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### Audio source separation

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Many sound scenes are mixtures of several concurrent sound sources.

When facing such scenes, humans are able to perceive and focus on individual sources.

Source separation is the problem of recovering the source signals underlying a given mixture.

It is a core problem of audio signal processing, with applications such as:

hearing aids,

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- post-production, remixing and 3D upmixing,
- spoken/multimedia document retrieval,
- MIR.

### The data at hand

As an inverse problem, source separation requires some knowledge.

Music is among the most difficult application areas of source separation because of the wide variety of sources and mixing processes.



### Music sources

Music sources include acoustical or virtual instruments and singing voice.

Sound is produced by transmission of one or more excitation movements/signals through a resonant body/filter.

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This results in a wide variety of sounds characterized by their:

- polyphony (monophonic or polyphonic)
- temporal shape (transitory, constant or variable)
- spectral fine structure (random or pitched)
- spectral envelope



### Effects of microphone recording

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For point sources, room acoustics result in filtering of the source signal



where the intensity and delay of direct sound are functions of the source position relative to the microphone.

Diffuse sources (piano, drums) amount to (infinitely) many point sources.

The mixture signal is equal to the sum of the contributions of all sources at each microphone.

### Software mixing effects

Usual software mixing effects include:

- compression and equalization
- panning, *i.e.* channel-dependent intensity scaling
- reverb
- polarity and autopan

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The latter are widely employed to achieve perceptual envelopment, whereby even point sources are mixed diffusely.

Again, the intensity of direct sound is a function of the source position and the mixture signal is equal to the sum of the contributions of all sources in each channel.

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### Overview

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Hundreds of source separation systems were designed in the last 20 years. . .

... but few are yet applicable to real-world music, as illustrated by the 2008 and 2010 Signal Separation Evaluation Campaigns (SiSEC).

The wide variety of techniques boils down to three modeling paradigms:

- computational auditory scene analysis (CASA),
- probabilistic linear modeling, including independent component analysis (ICA) and sparse component analysis (SCA),
- probabilistic variance modeling, including hidden Markov models (HMM) and nonnegative matrix factorization (NMF).

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### Computational auditory scene analysis (CASA)

CASA aims to emulate the human auditory system.



Source formation relies on the *Gestalt* rules of cognition:

- proximity,
- similarity,
- continuity,
- closure,
- common fate. E. Vincent & N. Ono (INRIA & UTok

### Auditory front-end

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The sound signal is first converted into an auditory nerve representation via a series of processing steps:

- outer- and middle-ear: filter
- cochlear traveling wave model: filterbank
- haircell model: halfwave rectification + bandwise compression + cross-band suppression



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### Sinusoidal+noise decomposition

Many systems further decompose the signal into a collection of sinusoidal tracks plus residual noise.

This decomposition is useful to

- reduce the number of sound atoms to be grouped into sources,
- enable the exploitation of advanced cues, *e.g.* amplitude and frequency modulation.



Spatial cues

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Spatial proximity is assessed by comparing the observed

tational auditory scene analysis

- interchannel time difference (ITD),
- interchannel intensity difference (IID).



Note: in practice, most systems consider only binaural data, *i.e.* recorded by in-ear microphones.

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#### Spectral cues

The Gestalt rules also translate into e.g.

- common pitch and onset time,
- similar spectral envelope,
- spectral and temporal smoothness,
- lack of silent time intervals,

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• correlated amplitude and frequency modulation.

Most effort has been devoted to the estimation of pitch by cross-correlation of the auditory nerve representation in each band.



### Learned cues

In addition to the above primitive cues, the auditory system relies on a range of learned cues to focus on a given source:

- veridical expectation (episodic memory): "I know the lyrics"
- schematic expectation (semantic memory): "The inaudible word after *love you* must be *babe*"
- dynamic adaptive expectation (short-term memory): "This melody already occurred in the song"
- conscious expectation

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### Source formation and signal extraction

Each time-frequency bin or each sinusoidal track is associated to a single source according to the above cues: this is known as binary masking.

Individual cues are ambiguous, e.g.

- the observed IID/ITD may be due to a single source in the associated direction or to several concurrent sources around that direction,
- a given sinusoidal track may be a harmonic of different sources.

Most systems exploit several cues with some precedence order or weighting factors determined by psycho-acousticians.



### Summary of CASA

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#### Advantages:

- wide range of spectral, spatial and learned cues
- robustness thanks to joint exploitation of several cues

Limitations:

- musical noise artifacts due to binary masking
- suboptimal cues, designed for auditory scene analysis instead of machine source separation
- practical limitation to a few spectral and/or spatial cues, with no general framework for the integration of additional cues
- (historically) bottom-up approach, prone to error propagation, and limitation to pitched sources

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no results within recent evaluation campaigns

Model-based audio source separation

- Source separation and music
- Computational auditory scene analysis
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The alternative top-down approach consists of finding the source signals that best fit the mixture and the expected properties of audio sources.

In a probabilistic framework, this translates into

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- building generative models of the source and mixture signals,
- inferring latent variables in a maximum a posteriori (MAP) sense.

### Linear modeling

The established linear modeling paradigm relies on two assumptions:

- oint sources
- Iow reverberation

Under assumption 1, the sources and the mixing process can be modeled as single-channel source signals and a linear filtering process.

Under assumption 2, this filtering process is equivalent to complex-valued multiplication in the time-frequency domain via the short-time Fourier transform (STFT).

In each time-frequency bin (n, f)

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 $\mathbf{X}_{nf} = \sum_{i=1}^{J} S_{jnf} \mathbf{A}_{jf}$ 

 $\mathbf{X}_{nf}$ : vector of mixture STFT coeff. J: number of sources  $S_{jnf}$ : jth source STFT coeff.  $\mathbf{A}_{jf}$ : jth mixing vector

### Priors over the mixing vectors

The mixing vectors  $\mathbf{A}_{jf}$  encode the apparent sound direction in terms of • ITD  $\tau_{if}$ ,

• IID g<sub>if</sub>.

For non-echoic mixtures, ITDs and IIDs are constant over frequency and related to the direction of arrival (DOA)  $\theta_i$  of each source

$$\mathbf{A}_{jf} \propto \begin{pmatrix} 1 \\ g_j e^{-2i\pi f \tau_j} \end{pmatrix}$$

For echoic mixtures, ITDs and IIDs follow a smeared distribution  $P(\mathbf{A}_{if}|\theta_i)$ 



#### I.i.d. priors over the source STFT coefficients

Most systems assume that the sources have random spectra, *i.e.* their STFT coefficients  $S_{jnf}$  are independent and identically distributed (i.i.d.).

The magnitude STFT coefficients of audio sources are sparse: at each frequency, few coefficients have large values while most are close to zero.

This property is well modeled by the generalized exponential distribution



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Note: coarser binary activity priors have also been employed.

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### Inference algorithms

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Given the above priors, source separation is typically achieved by joint MAP estimation of the source STFT coefficients  $S_{jnf}$  and other latent variables ( $\mathbf{A}_{if}$ ,  $g_i$ ,  $\tau_i$ , p,  $\beta_i$ ) via alternating nonlinear optimization.

This objective is called sparse component analysis (SCA).

For typical values of p, the MAP source STFT coefficients are nonzero for at most two sources in a stereo setting.

When the number of sources is J = 2, SCA is renamed nongaussianitybased frequency-domain independent component analysis (FDICA).

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Practical illustration of separation using i.i.d. linear priors

Probabilistic linear modeling

Time-frequency bins dominated by the center source are often erroneously associated with the two other sources.

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### SiSEC results on toy mixtures of 3 sources



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Summary of probabilistic linear modeling

#### Advantages:

• top-down approach

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• separation of more than one source per time-frequency bin

#### Limitations:

- restricted to mixtures of non-reverberated point sources
- separation of at most two sources per time-frequency bin
- musical noise artifacts due to the ambiguities of spatial cues
- no straightforward framework for the integration of spectral cues

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#### Idea 1: from sources to mixture components

Diffuse or semi-diffuse sources cannot be modeled as single-channel signals and not even as finite dimensional signals.

Instead of considering the signal produced by each source, one may consider its contribution to each channel of the mixture signal.

Source separation becomes the problem of estimating the multichannel mixture components underlying the mixture.

In each time-frequency bin (n, f)

$$\mathbf{X}_{nf} = \sum_{i=1}^{J} \mathbf{C}_{jnf}$$

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 $X_{nf}$ : vector of mixture STFT coeff. J: number of sources  $C_{jnf}$ : jth mixture component

#### Idea 2: translation and phase invariance

In order to overcome the ambiguities of spatial cues, additional spectral cues are needed as shown by CASA.

Most audio sources are translation- and phase-invariant: a given sound may be produced at any time with any relative phase across frequency.

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### Variance modeling

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Variance modeling combines these two ideas by modeling the STFT coefficients of individual mixture components by a circular multivariate distribution whose parameters vary over time and frequency.

The non-sparsity of source STFT coefficients over small time-frequency regions suggests the use of a non-sparse distribution.



### Choice of the distribution

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For historical reasons, several distributions have been preferred in a mono context, which can equivalently be expressed as divergence functions over the source magnitude/power STFT coefficients:

- Poisson  $\leftrightarrow$  Kullback-Leibler divergence aka I-divergence
- $\bullet$  tied-variance Gaussian  $\leftrightarrow$  Euclidean distance
- $\bullet \ \ \text{log-Gaussian} \leftrightarrow \text{weighted log-Euclidean distance}$

These distributions do not easily generalize to multichannel data.

### The multichannel Gaussian model

The zero-mean Gaussian distribution is a simple multichannel model.

$$P(\mathbf{C}_{jnf}|\mathbf{\Sigma}_{jnf}) = \frac{1}{\det(\pi \mathbf{\Sigma}_{jnf})} e^{-\mathbf{C}_{jnf}^{H} \mathbf{\Sigma}_{jnf}^{-1} \mathbf{C}_{jnf}} \qquad \begin{array}{l} \mathbf{\Sigma}_{jnf}: \ jth \ \text{component} \\ \text{covariance matrix} \end{array}$$

The covariance matrix  $\Sigma_{jnf}$  of each mixture component can be factored as the product of a scalar nonnegative variance  $V_{jnf}$  and a mixing covariance matrix R<sub>if</sub> respectively modeling spectral and spatial properties

$$\mathbf{\Sigma}_{inf} = V_{inf} \mathbf{R}_{if}$$

Under this model, the mixture STFT coefficients also follow a Gaussian distribution whose covariance is the sum of the component covariances

$$P(\mathbf{X}_{nf}|V_{jnf},\mathbf{R}_{jf}) = \frac{1}{\det\left(\pi\sum_{j=1}^{J}V_{jnf}\mathbf{R}_{jf}\right)}e^{-\mathbf{X}_{nf}^{H}\left(\sum_{j=1}^{J}V_{jnf}\mathbf{R}_{jf}\right)^{-1}\mathbf{X}_{nf}}$$

### General inference algorithm

Independently of the priors over  $V_{jnf}$  and  $\mathbf{R}_{jf}$ , source separation is typically achieved in two steps:

- joint MAP estimation of all model parameters using the expectation maximization (EM) algorithm,
- MAP estimation of the source STFT coefficients conditional to the model parameters by multichannel Wiener filtering

$$\widehat{\mathbf{C}}_{jnf} = V_{jnf} \mathbf{R}_{jf} \left( \sum_{j'=1}^{J} V_{j'nf} \mathbf{R}_{j'f} \right)^{-1} \mathbf{X}_{nf}$$

### Rank-1 priors over the mixing covariances

The mixing covariances  $\mathbf{R}_{i\!f}$  encode the apparent spatial direction and spatial spread of sound in terms of

• ITD,

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IID,

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• normalized interchannel correlation a.k.a. interchannel coherence.

For non-reverberated point sources, the interchannel coherence is equal to one, *i.e.* **R**<sub>*j*f</sub> has rank 1

$$\mathbf{R}_{jf} = \mathbf{A}_{jf} \mathbf{A}_{jf}^{H}$$

The priors  $P(\mathbf{A}_{if}|\theta_i)$  used with linear modeling can then be simply reused.

### Full-rank priors over the mixing covariances

For reverberated or diffuse sources, the interchannel coherence is smaller than one, *i.e.* **R**<sub>if</sub> has full rank.

The theory of statistical room acoustics suggests the direct+diffuse model

 $\lambda_i$ : direct-to-reverberant ratio  $\mathbf{R}_{if} \propto \lambda_i \mathbf{A}_{if} \mathbf{A}_{if}^H + \mathbf{B}_f$ **A**<sub>*jf*</sub>: direct mixing vector  $\mathbf{B}_{f}$ : diffuse noise covariance

with

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$$\begin{split} \mathbf{A}_{jf} &= \sqrt{\frac{2}{1+g_j^2}} \begin{pmatrix} 1\\ g_j e^{-2i\pi f\tau_j} \end{pmatrix} & \tau_j: \text{ ITD or}\\ g_j: \text{ IID of}\\ \mathbf{B}_f &= \begin{pmatrix} 1 & \text{sinc}(2\pi fd/c)\\ \text{sinc}(2\pi fd/c) & 1 \end{pmatrix} & c: \text{ sound } \end{split}$$

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- f direct sound direct sound
- hone spacing speed

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### l.i.d. priors over the source variances

Baseline systems rely again on the assumption that the sources have random spectra and model the source variances  $V_{jnf}$  as i.i.d. and locally constant within small time-frequency regions.

When these follow a mildly sparse prior, it can be shown that the MAP variances are nonzero for up to four sources.

Discrete priors constraining the number of nonzero variances to one or two have also been employed.

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When the number of sources is J = 2, this model is also called nonstationarity-based FDICA.

### Benefit of exploiting interchannel coherence

Interchannel coherence helps resolving some ambiguities of ITD and IID and identify the predominant sources more accurately.



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Practical illustration of separation using i.i.d. variance priors



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### Spectral priors based on template spectra

Variance modeling enables the design of phase-invariant spectral priors.

The Gaussian mixture model (GMM) represents the variance  $V_{jnf}$  of each source at a given time by one of K template spectra  $w_{jkf}$  indexed by a discrete state  $q_{jn}$ 

$$V_{jnf} = w_{jq_{in}f}$$
 with  $P(q_{jn} = k) = \pi_{jk}$ 

Different strategies have been proposed to learn these spectra:

- speaker-independent training on separate single-source data,
- speaker-dependent training on separate single-source data,
- MAP adaptation to the mixture using model selection or interpolation,
- MAP inference from a coarse initial separation.

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### Spectral priors based on basis spectra

The GMM does not efficiently model polyphonic musical instruments.

The variance  $V_{jnf}$  of each source is then better represented as the linear combination of K basis spectra  $w_{jkf}$  multiplied by time-varying scale factors  $h_{jkn}$ 

$$V_{jnf} = \sum_{k=1}^{K} h_{jkn} w_{jkf}$$

This model is also called nonnegative matrix factorization (NMF).

Again, a range of strategies have been used to learn these spectra:

• instrument-dependent training on separate single-source data,

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- MAP adaptation to the mixture using uniform priors,
- MAP adaptation to the mixture using trained priors.

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Practical illustration of separation using basis spectra



### Constrained template/basis spectra

 $\mathsf{MAP}$  adaptation or inference of the template/basis spectra is often needed due to

• the lack of training data,

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• the mismatch between training and test data.

However, it is often inaccurate: additional constraints over the spectra are needed to further reduce overfitting.

### Harmonicity and spectral smoothness constraints

For instance, harmonicity and spectral smoothness can be enforced by

- associating each basis spectrum with some a priori pitch p
- modeling w<sub>jpf</sub> as the sum of fixed narrowband spectra b<sub>plf</sub> representing adjacent partials at harmonic frequencies scaled by spectral envelope coefficients e<sub>ipl</sub>

$$w_{jpf} = \sum_{l=1}^{L_p} e_{jpl} b_{plf}$$

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Parameter estimation now amounts to estimating the active pitches and their spectral envelopes instead of their full spectra.

### Practical illustration of harmonicity constraints



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#### Further constraints

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Further constraints that have been implemented in this context include

- source-filter model of instrumental timbre,
- inharmonicity and tuning.

Probabilistic priors are also popular:

• state transition priors

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$$P(q_{jn}=k|q_{j,n-1}=l)=\pi_{jkl}$$

• spectral continuity priors (for percussive sounds)

$$\mathcal{P}(V_{jnf}|V_{jn,f-1}) = \mathcal{N}(V_{jnf};V_{jn,f-1},\sigma_{ ext{perc}})$$

• temporal continuity priors (for sustained sounds)

$$P(V_{jnf}|V_{j,n-1,f}) = \mathcal{N}(V_{jnf}; V_{j,n-1,f}, \sigma_{\text{sust}})$$







### Summary of probabilistic variance modeling

#### Advantages:

• top-down approach

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- virtually applicable to any mixture, including to diffuse sources
- no hard constraint on the number of sources per time-frequency bin
- fewer musical noise artifacts by joint exploitation of spatial, spectral and learned cues
- principled modular framework for the integration of additional cues

Limitations:

- remaining musical noise artifacts
- current implementations limited to a few spectral and/or spatial cues...but this is gradually changing!

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• Source separation and music

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- Computational auditory scene analysis
- Probabilistic linear modeling
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### Summary principles of model-based source separation

Most model-based source separation systems rely on modeling the  $\mathsf{STFT}$  coefficients of each source as a function of

- a scalar variable  $(S_{jnf} \text{ or } V_{jnf})$  encoding spectral cues,
- a vector or matrix variable (A<sub>jf</sub> or R<sub>jf</sub>) encoding spatial cues.

Robust source separation requires priors over both types of cues:

- spectral cues alone cannot discriminate sources with similar pitch range and timbre,
- spatial cues alone cannot discriminate sources with the same DOA.

A range of informative priors have been proposed, relating for example

- S<sub>jnf</sub> or V<sub>jnf</sub> to discrete or continuous latent states,
- A<sub>jf</sub> or R<sub>jf</sub> to the source DOAs.

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Variance modeling outperforms linear modeling.

### Conclusion and remaining challenges

To sum up, source separation is a core problem of audio signal processing with huge potential applications.

Existing systems are gradually finding their way into the industry, especially for applications that can accomodate

- a certain amount of musical noise artifacts, such as MIR,
- partial user input/feedback, such as post-production.

We believe that these two limitations could be addressed in the next 10 years by exploiting the full power of probabilistic modeling, especially by:

• integrating more and more spatial and spectral cues,

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• making a better use of learned cues, using training data or repeated sounds

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2008 and 2010 Signal Separation Evaluation Campaigns http://sisec.wiki.irisa.fr/

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Music Source Separation
and its Applications to MIR

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### Outline

- Introduction
- Part I: Brief Introduction of State-of-the-arts
  - Singer/Instrument Identification
  - Audio Tempo Estimation
- Part II: Harmonic/Percussive Sound Separation
  - Motivation and Formulation
  - Open Binary Software
- Part III: Applications of HPSS to MIR Tasks
  - Audio Chord Estimation
  - Melody Extraction
  - Audio Genre Classification
- Conclusions
- Solf Aug. 9, 2010

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Introduction	Sector for the University
<ul> <li>Focus of the second half of this tutorial is to clarify</li> <li>What source separation has been used for MIR?</li> <li>How does it improve performance of MIR tasks?</li> </ul>	Part I: Brief Introduction of State-of-the-arts
<ul> <li>Examples:</li> </ul>	
<ul> <li>Multi pitch estimation Task itself is tightly coupled with source separation.</li> </ul>	
<ul> <li>Audio genre classification How source separation is useful? Not straightforward.</li> </ul>	
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### Vocal Separation Based on Melody Transcriber

- Melody-F0-based Vocal Separation [Mesaros2007]
  - Estimate melody-F0 by melody transcription system [Ryynanen2006].
  - Generate harmonic overtones at multiple of estimated F0.
  - Estimate amplitudes and phases of overtones based on cross correlation between original signal and complex exponentials.
- They evaluate the effect of separation in singer identification performance using by different classifiers.

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### **Evaluation by Identification Rate**





Singing to Accompaniment Ratio: -5dB Singing to Accompaniment Ratio: 15dB Generated by Table 1 and 2 [Mesaros2007]

Performance is much improved, especially in low singing-to-accompaniment ratio. ISMIR2010 Tutorial 1 Aug. 9, 2010

### **Instrument Identification**

- Task: Determine instruments present in music piece
- Typical approach



### Feature Weighting [Kitahara2007]

- Feature vectors of each instrument are collected from polyphonic music for training.
- Robustness of each feature is evaluated by ratio of intra-class variance to inter-class variance: Applying Linear discriminant analysis (LDA) for feature weighting.





# Applying Harmonic+Noise Model





### Influence of S+N Model

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### Separation based on H+N model shows better results.

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# **Motivation and Goal of HPSS**

Motivation: Music consists of two different components



harmonic component 🐗

- Goal: Separation of a monaural audio signal into harmonic and percussive components
- Target: MIR-related tasks
  - multi-pitch analysis, chord recognition... H-related
  - beat tracking, rhythm recognition... P-related

### **Related Works to H/P Separation** Source separation into multiple components

- followed by classification
  - ICA and classification [Uhle2003]
  - NMF and classification [Helen2005]
- Steady + Transient model
  - Adaptive phase vocoder
  - Subspace projection
  - Matching persuit
  - ...etc

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Good review is provided in [Daudet2005]

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Baysian NMF [Dikmen2009]

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### Formulation of H/P Separation (1/2)

- Formulation as an Optimization Problem:
  - Objective function to minimize

$$J(\boldsymbol{H},\boldsymbol{P}) = \underline{D(\boldsymbol{W},\boldsymbol{H}+\boldsymbol{P})} + \underline{C_H(\boldsymbol{H})} + \underline{C_P(\boldsymbol{P})}$$

Closeness cost Smoothness cost

$$H_{t,\omega} \ge 0$$
$$P_{t,\omega} \ge 0$$

In MAP estimation context, they are corresponding likelihood term and prior term, respectively.

### Formulation of H/P Separation (2/2)

Closeness cost function: I-divergence

$$D(\boldsymbol{W}, \boldsymbol{H} + \boldsymbol{P}) = \sum_{\omega, \tau} \left\{ W_{\omega, \tau} \log \frac{W_{\omega, \tau}}{H_{\omega, \tau} + P_{\omega, \tau}} - W_{\omega, \tau} + H_{\omega, \tau} + P_{\omega, \tau} \right\}$$

Smoothness cost function: Square of difference

$$C_{H}(\boldsymbol{H}) = \sum_{\omega,\tau} \frac{1}{2\sigma_{H}^{2}} (H_{\omega,\tau-1}^{\gamma} - H_{\omega,\tau}^{\gamma})^{2} \qquad \gamma = 0.5$$
  
for scale invariance  
$$C_{P}(\boldsymbol{H}) = \sum \frac{1}{2\sigma^{2}} (P_{\omega-1,\tau}^{\gamma} - P_{\omega,\tau}^{\gamma})^{2}$$

 $\frac{2\sigma_P^2}{\omega_{\tau}\tau} \frac{2\sigma_P^2}{\omega_{\tau}\tau}$  Weights to control two smoothness

A variance modeling-based separation using

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- Poisson observation distribution
- Gaussian continuity priors

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[Miyamoto2008, Ono2008, etc]

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### **Update Rules**

- Update alternatively two kinds of variables:
  - H and P:  $H_{\omega,\tau} \leftarrow \left(\frac{b_{H_{\omega,\tau}} + \sqrt{b_{H_{\omega,\tau}}^2 + 4a_{H_{\omega,\tau}}c_{H_{\omega,\tau}}}}{2a_{H_{\omega,\tau}}}\right)^2$   $P_{\omega,\tau} \leftarrow \left(\frac{b_{P_{\omega,\tau}} + \sqrt{b_{P_{\omega,\tau}}^2 + 4a_{P_{\omega,\tau}}c_{P_{\omega,\tau}}}}{2a_{P_{\omega,\tau}}}\right)^2$ • Auxiliary variables:  $m_{P_{\omega,\tau}} = \frac{P_{\omega,\tau}}{H_{\omega,\tau} + P_{\omega,\tau}} \qquad m_{H_{\omega,\tau}} = \frac{H_{\omega,\tau}}{H_{\omega,\tau} + P_{\omega,\tau}}$   $a_{P_{\omega,\tau}} = \frac{2}{\pi^2} + 2 \qquad a_{H_{\omega,\tau}} = \frac{2}{\pi^2} + 2$

$$b_{P\omega,\tau} = \frac{(\sqrt{P_{\omega-1,\tau}} + \sqrt{P_{\omega+1,\tau}})}{\sigma_P^2} \qquad b_{H\omega,\tau} = \frac{(\sqrt{H_{\omega,\tau-1}} + \sqrt{H_{\omega,\tau+1}})}{\sigma_H^2}$$
$$c_{P\omega,\tau} = 2m_{P\omega,\tau}W_{\omega,\tau} \qquad c_{H\omega,\tau} = 2m_{H\omega,\tau}W_{\omega,\tau}$$

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### **Separated Examples**

Music piece	original	н	Р
RWC-MDB-P-7 "PROLOGUE "	4	4	4
RWC-MDB-P-12 "KAGE-ROU "			
RWC-MDB-P-18 "True Heart"			
RWC-MDB-P-25 "tell me"	4	4	4
RWC-MDB-J-16 "Jive "	4	4	

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# **Real-Time Implementation**

Sliding Block Analysis



### **Open Software: Real-time H/P equalizer**

Available at http://www.hil.t.u-tokyo.ac.jp/software/HPSS/

- Control H/P balance of audio signal in real time
- Simple instructions:
  - 1) Click "Load WAV" button and choose a WAVformatted audio file.
  - 2) Click "Start" button, and then, audio starts.
  - Slide H/P balance bar as you like and listen how the sound changes.



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### III-1: Audio Chord Detection

### **Audio Chord Detection**

Task: Estimate chord sequence and its segmentation from music audio



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# **Tuning Compensation**

- Tuning difference among songs
  - Neglecting this may blur chroma features
- Choose best tuning from multiple candidates
  - Find maximum chroma energy (sum of all bins of chroma)
  - Assume: tuning does not change within a song



### **Delta Chroma Features** Improve chord boundary accuracy by features representing chord boundaries

- Chord tones largely changes at chord boundary
  - Delta chroma: derivative of chroma features
  - Cf. Delta cepstrum (MFCC): Effective features of speech recognition
- Calculated by regression analysis of  $\delta$  sample points [Sagayama&Itakura1979]



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#### **Experimental Evaluation Multiple States per Chord** Test Data Chroma changes from "onset" to "release" 180 songs (12 albums) of The Beatles (chord reference capture the change by having multiple states per chord annotation provided by C. Harte) tradeoff between data size and the number of states 11.025 kHz sampling, 16bit, 1ch, WAV file Frequency range: 55.0Hz-1661.2Hz (5 octaves) Labels 12 × major/minor =24 chords + N (no chord) Evaluation С Album filtered 3-fold cross validation oitch 8 albums for training, 4 albums for testing Frame Recognition Rate = (#correct frames) / (#total frames) Sampled every 100ms time Solf Aug. 9, 2010 ISMIR2010 Tutorial 1 Aug. 9, 2010 ISMIR2010 Tutorial 1 37 SOAR





#### Is voice harmonic or percussive? HPSS results with different frame length Depends on spectrogram resolution (frame-length) Example On short-frame STFT domain, voice appears as "H" ΗØ Ρ 🔕 Frame length: 16ms (time direction clustered). On long-frame STFT domain, voice appears as "P" (frequency direction clustered). Vocal P 🕖 Frame length: 512ms ΗØ "Harmonic' "Percussive" Self Aug. 9, 2010 ISMIR2010 Tutorial Solf Aug. 9, 2010 ISMIR2010 Tutorial



## **Spectrogram Example**

Voice-enhanced signal (by two-stage HPSS)



# **Separation Examples**

title	original	Extracted Vocal	Vocal Cancelled*	Genre
"tell me"	Ø,	Ø,	0,	F, R&B
"Weekend"	Ø,	Ø,	Ø,	F, Euro beat
"Dance Together"	Ø,	0,	0,	M, Jazz
"1999"	Ø,	Ø,	Ø,	M, Metal rock
"Seven little crows"	O,	Ø,	Ø,	F, Nursery rhyme
"La donna è mobile" from Verdi's opera "Rigoletto"	O,	O,	Ø,	M, Classical

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#### **Experimental Evaluation** Features and Classifiers Dataset Feature Vectors: (standard) (rhythm-intensive) GTZAN dataset Ballroom dataset Genre-pattern Occurrence Histogram (normalized) 22050Hz sampling, 1ch 22050Hz sampling, 1ch Classifier: Support Vector Machine (SVM) 30 seconds clips 30 seconds clips 8 styles 10 genres {blues, classical, country, disco, {chacha, foxtrot, quickstep, 4/7 hiphop, jazz, metal, pop, reggae, rumba, samba, tango, rock} viennesewaltz, waltz} 100 songs per genre: total o 100 songs per style: total 1/7 1000 songs 800 songs Evaluation 2/7 2 10-fold cross-validation Histogram Normalize Classifier: linear SVM (toolkit "Weka" used) 61 ISMIR2010 Tutorial . SO Aug. 9, 2010 61 Aug. 9, 2010 ISMIR2010 Tutorial 1

## **Extracted Percussive Patterns**

Pattern set

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 Divided the datasets into 2 parts and obtained 2 sets of 10 templates for each genre

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Example of learned templates classical

	country	147.119.00.00.00
Landa a Branderski bigi bri ballan i	disco	100182-019
terneter and the second s	hiphop	181 / 11 ADB FORK 1
A CARLES A COLUMN TO A CARLES AND AND A	jazz	والملافية فيتراط والم
A CONTRACTOR OF	metal	SHALLONGING
the second second second second	рор	and the first of the
10 templates learned from "blues"	reggae	
	rock	the state later

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## **Genre Classification Accuracy**

Percussive pattern feature only

•		
Features [number of dim.]	GTZAN dataset	Ballroom dataset
Baseline (Random)	10.0%	12.5%
Rhythmic (from template set #1) [10/8]	43.6%	54.0%
Rhythmic (from template set #2) [10/8]	42.3%	55.125%

- Merged with timbral features
  - Statistic features such as MFCC, etc. (68 dim.) [Tzanetakis 2008]
  - Performed well on audio classification tasks in MIREX 2008

		Features [number of dim.] GTZAN dataset		Ballroom datase			
			Existing (Timbre) [68]		72.4%		57.625%
		Merged (from te	mplate set #1) [78/76]	-	76.1%		70.125%
		Merged (from te	mplate set #2) [78/76]		76.2%		69.125%
Classification accuracy is improved by combining percussive pattern features.							
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### Conclusions

- Source separation techniques used to MIR
  - F0-based harmonic separation
  - Non-negative matrix factorization or PLCA
  - Sinusoid + Noise model
  - Harmonic/percussive sound separation
- Source separation is useful
  - To enhance specific components
  - To increase the number of channels and the dimension of feature vectors
  - To generate new features

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### **Future Works**

- Application of source separation to other MIR tasks
  - Cover song identification, audio music similarity,...
- Improvement of separation performance itself by exploiting musicological knowledge
- Using spatial (especially stereo) information
  - Current works are limited to monaural separation
- Feature weighting technique for overcoming errors due to imperfect source separation

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# **Reference Book Chapter**

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### Available Separation Softwares

- Harmonic Percussive Sound Separation (HPSS)
   <u>http://www.hil.t.u-tokyo.ac.jp/software/HPSS/</u>
- ICA Central: Early software restricted to mixtures of two sources
  - http://www.tsi.enst.fr/icacentral/algos.html
- SiSEC Reference Software: Linear modeling-based software for panned or recorded mixtures
  - http://sisec2008.wiki.irisa.fr/tiki-index.php?page=Underdetermined+speech+and+music+mixtures
- QUAERO Source Separation Toolkit: Modular variancemodeling based software implementing a range of structures: GMM, NMF, source-filter model, harmonicity, diffuse mixing, etc
  - To be released Fall 2010: watch the music-ir list for an announcement!

### Advertisement: LVA/ICA 2010



- LVA/ICA 2010 is held will be held in St. Malo, France on September 27-30, 2010.
- More than 20 papers on music and audio source separation will be presented.

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